

In the Specification

Please replace paragraphs [0001] through [0003] with the following:

Related Application

This is a §371 of International Application No. PCT/FR2003/002630, with an international filing date of September 2, 2003 (WO 2004/021888, published March 18, 2004), which is based on French Patent Application No. 02/11074, filed September 6, 2002.

Field of the Invention

~~The present~~This invention relates to a device and a process for measuring the elasticity of a human or animal organ, or more generally all viscoelastic environments presenting an ultrasonic signal after ultrasonic illumination and the consecutive establishing of a two- or three-dimensional representation of the elasticity. It concerns in particular but not exclusively the measuring of the elasticity of a human breast. The significance of this technique is that the pathological nature of the tissues is frequently related to their elasticity.

Background

~~French patent application~~ FR 2733142 ~~known in the prior art~~ discloses a device for measuring elasticity that realizes a measuring in 2 dimensions but is also suitable for realizing measurements in three dimensions. However, this device does not comprise a scanning means suitable for performing the scanning with the bar or bars in two perpendicular directions.

Moreover, ~~US patents~~ US 6,176,827; US 5,099,848; US 2002/01098; US 6,277,074 and US 5,474,070 ~~are known that all~~ disclose solutions for making only one measurement in two dimensions, at times with a fixed bar (cf. US 6,176,827).

Please replace paragraphs [0005] through [0012] with the following:

Furthermore, as concerns the measuring of elasticity in two dimensions, the article “Shear Modulus Imaging with 2D Transient Elastography” by L. Sandrin, M. Tanter, S. Catheline and M. Fink in Ultrason. Ferroelectr. Freq. Control, vol. 49 (4), pp. 426-435 (2002) is known and describes a technique for measuring elasticity and a representation in two dimensions of this measuring. The resolution of the inverse problem, that is to say, ~~consisting in~~ going back to the parameters that describe the viscoelastic environment to be measured, is imperfect here because the displacement is not known in the three spatial directions. In fact, according to the computational algorithms connected to the measurements carried out by the device presented in ~~this~~that article, the operators are obliged to formulate hypotheses ~~in order~~ to resolve the calculations of elasticity, but practice has demonstrated that these hypotheses are seldom justified.

~~International patent application No. WO 0070362 is also known and describes~~discloses a system using magnetic resonance elastography (ERM), in which a viscoelastic zone (such as the human chest) is excited by mechanical waves. The subject matter of ~~this~~that invention is based on the hypothesis that the results of the measurements by ERM are solutions independent of the time of the partial differential equations precisely describing the behavior of mechanical waves in a viscoelastic material (including for longitudinal waves and in a reflecting environment). To this end the Young module contained in these equations can be calculated. In addition, it proposes using (in a predominant manner) longitudinal waves, that are capable of penetrating into the human chest, which is not the case for transversal waves. In ~~the~~that device, ~~of this patent application the obtaining of the elasticity map requires much time. Furthermore, the cost of implementing~~ ~~this~~that device is very high.

~~Moreover, it is clear that measuring the elasticity in larger dimensions constitutes a considerable advantage, which significant improvement of the state of the art is obtained by virtue of the device in accordance with the invention.~~

~~The prior art is also constituted by international patent application~~International Application
No. FR 9903157 ~~that describes~~discloses an imaging process for observing the propagation of an impulsive wave of low-frequency shearing at the same time in a multitude of points of a viscoelastic diffusing environment. To this end ultrasonic compression waves are emitted ~~in this device~~ at an ultrarapid cadence that allows the obtention of a succession of images of the environment. Then, the images obtained ~~in this manner~~ are processed in non-real time by intercorrelation ~~in order to~~ determine at each point of each image the movements of the environment during the propagation of the shearing wave.

~~This~~That invention ~~does~~is not ~~satisfy~~satisfactory because it requires envisaging two hypotheses: ~~The~~the second derivative of the displacement is considered to be zero in the direction orthogonal to the plane, and ~~The~~the environment is assumed to be perfectly incompressible.

Summary of the Invention

This invention relates to a device for measuring elasticity of a human or animal organ, or viscoelastic environments presenting an ultrasonic signal after ultrasonic illumination and consecutively establishing a representation in two or three dimensions of the elasticity, including at least one ultrasonic bar including a plurality of transducers, an excitor that generates and delivers a low-frequency, direct or indirect applied force, a receiver that acquires ultrasonic signals, a controller that commands and processes data, and a scanner that carries out scanning with the bar in one dimension (1D) or in two dimensions (2D) in two perpendicular directions, respectively, to obtain a representation of the measure of the elasticity in two (2D) or three dimensions (3D).

This invention also relates to a process for measuring elasticity of a human or animal organ, or viscoelastic environments presenting an ultrasonic signal after ultrasonic illumination and consecutively establishing a representation in two or three dimensions of the elasticity, including generating a low-frequency applied force or signal with an ultrasonic bar and acquiring ultrasonic signals, displacing the bar with a scanner in two perpendicular directions, generating ultrasonic images, calculating tissular speeds, and inverting the data by recovering parameters describing the viscoelastic environment.

Brief Description of the Drawings

The invention will be described in the following by way of non-limiting example with reference made to the attached drawings.

Fig. 1 is a schematic diagram showing the displacement of an echographic bar of the device of the invention provided with a simple mechanical scanning means.

Fig. 2 is a schematic diagram showing the displacement of an echographic bar of the device of the invention provided with a double mechanical scanning means.

Fig. 3 is a schematic diagram showing the functioning of a 1.5 D bar of the device of the invention provided with a means for scanning by ultrasonic focalization in elevation.

Fig. 4 is a schematic diagram showing the device of the invention provided with a 1.5 or 1.75 D bar suitable for focusing in elevation.

Fig. 5 is a front elevational view showing the device of the invention provided with a wye transducer in which the transducers are spatially distributed.

Fig. 6 is a schematic diagram showing the device of the invention measuring the elasticity of the breast of a patient.

Fig. 7 is a schematic diagram showing one aspect of the device of the invention.

Detailed Description

~~Therefore, the~~ This invention has ~~the particular problem of remedying the~~ remedies disadvantages of the systems of the prior art. It ~~proposes to this end~~ provides a device for measuring the elasticity of a human or animal organ, in particular of a breast, or more generally all viscoelastic environments presenting an ultrasonic signal after ultrasonic illumination and the consecutive establishing of a representation in two or three dimensions of the elasticity, comprising at least one ultrasonic bar ~~+~~ comprising a plurality of transducers ~~+~~ or the like, an excitation means suitable for generating and delivering a low-frequency, direct or indirect applied force, a means for acquiring ultrasonic signals, a means for commanding and processing data such as a computer, ~~characterized in that it comprises~~ and a scanning means suitable for carrying out a scanning with the above-mentioned bar ~~+~~ in one dimension (1D) or in two dimensions (2D) in two perpendicular directions, respectively obtaining in this manner a representation of the measure of the elasticity in two (2D) or three dimensions (3D).

By means of these particularities the invention ~~can therefore propose~~ provides a device allowing the obtention of a mapping of the elasticity of the environment to be measured in two or three dimensions by virtue of a system that is relatively simple and inexpensive in comparison to ~~the~~ existing solutions.

Please replace paragraphs [0014] through [0016] with the following:

According to ~~a possibility offered by~~ one aspect of the invention the excitation means ~~consists of~~ comprises a mechanical vibration that can be transversal, longitudinal or more generally a mixture of both. The excitation means can advantageously ~~consist of~~ comprise one or several hyperthermal transducers because the elevation of the temperature produces displacements on the ultrasonic images either with the transducer(s) used for acquiring ultrasonic signals or one or several

transducers arranged around the viscoelastic environment. In the same manner, the excitation means can also ~~consist of~~comprise internal movements of the human or animal body such as, e.g., the beating of the heart.

According to another ~~possibility offered by~~aspect of the invention the excitation means ~~consists of~~comprises a remote palpation using the pressure of radiation either with the transducer(s) used for acquiring ultrasonic signals or one or several transducers arranged around the viscoelastic environment.

Please replace paragraphs [0018] through [0030] with the following:

The ultrasonic bar is advantageously a 1.5 D bar or a wye transducer allowing a focusing at a plurality of different points of elevation. In this instance the scanning is realized by ultrasonic focalization. ~~It is appropriate to recall here that a~~A “1.5 D bar,” as it is called in the art ~~of the invention~~, is a bar that is suitable not only for focusing along a plane but also in elevation relative to ~~this~~the plane, in the example along the horizontal plane parallel to the preceding one and slightly offset.

~~In order to~~To facilitate the comprehension of the invention it is also ~~recalled~~noted that an echographic bar with 0 D emits according to a linear dimension x, that a 1 D bar emits according to a two-dimensional plane x, y and finally that a 2 D bar customarily constituted ~~by~~of a multitude of ultrasonic transducers with a square shape distributed along a 2 D matrix permits the emission of ultrasound in a volume according to the three dimensions x, y and z.

According to ~~an embodiment~~one aspect of the invention the space between the ultrasonic bar and the above-mentioned viscoelastic environment is constituted at least in part ~~by~~of water or any other element suitable for assuring the free passage of ultrasonic waves.

The unit constituted ~~by~~of the ultrasonic transducers and their on-board electronic components is advantageously connected to the command and processing means by a very high-speed digital connection, e.g., of the LVDS type.

According to ~~an embodiment~~one aspect of the invention the device in accordance with the invention comprises two ultrasonic bars. According to ~~a realization of the device of the invention~~another aspect, the two bars are immersed in a hermetic container filled with a liquid, e.g., water. The hermetic container is advantageously connected to a rotation means suitable for rotating ~~this~~the container. According to ~~a possibility presented by~~another aspect of the invention the hermetic container can comprise a plurality of orifices into which a mechanical vibrator and/or an ultrasonic transducer is/are introduced. The orifices on or in the hermetic box are advantageously situated at 90° (degrees) from each other or the one from the other.

According to yet another embodiment~~aspect~~ of the invention the device in accordance with the invention comprises three bars suitable for measuring the tissular speeds along directions y, x and z.

The invention also relates to a process for measuring the elasticity of a human or animal organ, in particular a breast, or more generally all viscoelastic environments presenting an ultrasonic signal after ultrasonic illumination and the consecutive establishing of a representation in two or three dimensions of the elasticity, comprising at least one ultrasonic bar ~~1~~ or the like, excitation means suitable for generating low-frequency displacements, means for acquiring ultrasonic signals, means for commanding and processing data such as a computer, scanning means suitable for carrying out a scanning with the above-mentioned bar ~~1~~ in one dimension (1D) or in two dimensions (2D), respectively obtaining in this manner a representation of the measure of the elasticity in two (2D) or three dimensions (3D), ~~characterized in that it comprises~~comprising the following stages:

~~Generation~~generation of a low-frequency applied force or signal and the acquisition of ultrasonic signals,

~~Displacements~~displacement of the bar due to the scanning means in two perpendicular directions,

~~Calculation~~calculation of the ultrasonic images,

~~Calculations~~calculation of the tissular speeds,

~~Inversion~~inversion of the data ~~consisting in~~comprising recovering the parameters describing this viscoelastic environment.

The displacement stage of the bar is advantageously repeated as many times as is necessary ~~for acquiring~~to acquire all the ultrasonic data before passing to the stage of calculating the ultrasonic images.

Please replace paragraphs [0034] through [0046] with the following:

~~Embodiments of the invention will be described in the following by way of non-limiting example with reference made to the attached drawings.~~

~~Figure 1 shows the displacement of an echographic bar of the device of the invention provided with a simple mechanical scanning means.~~

~~Figure 2 shows the displacement of an echographic bar of the device of the invention provided with a double mechanical scanning means.~~

~~Figure 3 shows the functioning of a 1.5 D bar of the device of the invention provided with a means for scanning by ultrasonic focalization in elevation.~~

~~Figure 4 shows the device of the invention provided with a 1.5 or 1.75 D bar suitable for focusing in elevation.~~

~~Figure 5 shows the device of the invention provided with a wye transducer in which the transducers are spatially distributed.~~

~~Figure 6 shows the device of the invention measuring the elasticity of the breast of a patient.~~

~~Figure 7 schematically shows a realization of the device of the invention.~~

~~The~~Turning to the drawings, the attached figures do not represent all conceivable aspects of the ~~complete~~ device. ~~This~~The device comprises the usual elements for realizing measurements of the elasticity of a human or animal organ, that is to say, especially by means of an ultrasonic bar or probe comprising a plurality of transducers, electronic equipment suitable for assuring the acquisition of ultrasonic signals, control and processing means of the data such as a computer or the like an excitation means suitable for producing low-frequency displacements.

The invention relates to the use of a mechanical scanning means that assures the scanning of the above-mentioned ultrasonic bar. This allows, by means of the process of the invention, parameters to be measured that are not accessible via the devices of the prior art, in particular the prior art described in ~~patent No.~~FR 9903157. The parameters obtained in this manner are the second derivative of the displacement along the elevation, that is to say, the direction perpendicular to the plane of the image, and the two lacking components of the displacement vector.

The invention will be illustrated ~~in the following using~~by reference to a breast or any other organ that is ideally static as a human or animal organ ~~in order to~~ constitute the object of the measuring of elasticity with the device and the process in accordance with the ~~present~~ invention on the condition, of course, that an ultrasonic signal is presented after it was illuminated with the aid of ultrasonic signals. However, in the case in which the internal movements of the body cannot constitute a low-frequency applied force that can be used for the process, it is preferable that ~~this~~the organ is immobile in order not to disturb the measuring.

The process of the invention realizes the following steps in the following chronological order:

1. ~~The~~the generation of a low-frequency applied force or signal,
2. ~~The~~the acquisition of ultrasonic data,
3. ~~The~~the displacement of the bar by the scanning means,
4. ~~The~~the calculation of the ultrasonic images,
5. ~~The~~the calculation of the tissular speeds, also called displacement between successive images,
6. ~~Possible~~possible calculation of the tissular deformation speeds,
7. ~~Finally~~, inversion of the data, which allows the recovery of the parameters of the measured environment.

It should be noted that the calculating steps, that is, steps 4 to 6, can begin when the ultrasonic bar scans the viscoelastic environment, that is, that these steps ideally take place during the displacement of ~~this~~the bar.

Please replace paragraph [0048] with the following:

The various means that can be used to bring about low-frequency displacements can ~~consist~~ comprise a mechanical vibration realized by a vibrator that can be in particular one or several vibrating plates 20, piston(s) and/or bar(s). In the same manner, the excitation means suitable for generating a shearing wave can ~~consist of~~ comprise a remote palpation using the pressure of radiation either with the transducer(s) used for the acquisition of the ultrasonic signals or one or several transducers arranged around the object to be imaged.

Please replace paragraphs [0050] through [0057] with the following:

Then the stage of the displacement of the echographic or ultrasonic bar takes place. At ~~this~~

~~that stage, the scanning consisting of~~comprises shifting ~~this~~the bar is realized in three different manners as a function of the number and ~~of~~ the type of ultrasonic bar used.

Thus, the device in accordance with the invention can be equipped in particular with:

- ~~A~~a single ultrasonic, unidirectional bar 1,
- ~~Two~~two ultrasonic bars 5, 6 or one bar shifted along two axes,
- ~~An~~an ultrasonic bar of the 1.5 D 9 type.

In the case of a single ultrasonic, unidirectional bar 1, represented in ~~figure~~Fig. 1, echographic bar 1 is moved by a distance comprised between 10 μ m and 10 mm. At least one scan in one direction is carried out. For example, a scan is made in direction z, constituted by plane 2 while moving from Δz , constituted in the figure by the two planes 3, 4.

In the case of two ultrasonic bars 5, 6 represented in ~~figure~~Fig. 2 or equivalent to one bar moved in two axes 7, 8, two bars 5, 6 are used (or one successively). This scanning allows all the components of the tissular speed vector to be accessed.

In the case of an ultrasonic bar of type 1.5 D 9, represented in ~~figure~~Fig. 3, a mechanical scanning is avoided and the result is the same with a wye transducer. These two elements allow a focalizing in three different points of elevation. In the case of a 1.5 D 9 bar the shift along z is obtained by modifying the laws of focalization in such a manner as to change the elevation of the image plane.

During the course of the step of calculating the ultrasonic images these images are constructed using an algorithm of summation-delay as described in ~~patent~~International Application No. FR 9903157 cited above or using other types of rapid beamforming such as, e.g., the technique in space of spatial frequencies (see the article of J. Lu, "2D and 3D High Frame Rate Imaging with Limited Diffraction Beams", IEEE Trans. Ultrason. Ferroelectr. Freq. Contr., vol. 44, No. 4, 1997).

During the step of calculating the tissular speeds, also called “displacement between successive images,” the tissular speeds or displacements between two successive but not necessarily consecutive ultrasonic shots are measured by intercorrelation, described in ~~patent~~International Application No. FR 9903157 by Doppler, or by autocorrelation, described in particular in the article of C. Kasai, K. Namekawa, A. Koyano and R. Omoto, “Real-Time Two-Dimensional Blood Flow Imaging Using an Autocorrelation Technique”, IEEE Trans. Sonics Ultrason., vol. 35, pp. 458-464 (1985), and more generally by any other technique for measuring displacements.

When using a simple mechanical scanning ~~presented~~shown in ~~figure~~Fig. 1, at least the component along x of tissular speed V_x is accessed at each point of the environment situated in the imaged zone. When using an algorithm of the type described in the articles of E. E. Konofagou, J. Ophir, “A New Elastographic Method for Estimation and Imaging of Lateral Displacements, Lateral Strains, Corrected Axial Strains and Poisson’s Ratios in Tissues”, Ultrasound in Med. & Biol. 24, No. 8, pp. 1183-1199 (1998), and M. Tanter, J. Bercoff, L. Sandrin, M. Fink, “Ultrafast Compound Imaging for 2D Motion Vector Estimation: Application to Transient Elastography”, Ultrason. Ferroelectr. Freq. Control., the lateral component of tissular speed V_y can also be accessed. When using a double mechanical scan like the one represented in ~~figure~~Fig. 2 three components of the tissular speed are accessed: Bar 6 allows V_x and V_y to be measured and bar 5 allows V_y and V_z to be measured. The accuracy of the estimation of V_y is increased by calculating the half sum of the estimations with the two bars 5 and 6.

Please replace paragraph [0059] with the following:

The inversion step of the data ~~consists in~~comprises resetting or recovering the parameters that describe the viscoelastic environment. If the linear and isotropic environment is considered, these parameters are two in number. Shearing module μ and compression module λ can be selected. In

practice, in the soft tissues λ is on the order of the Gpa and varies very little. μ is on the order of the Kpa. The elasticity or Young module is equal in a first approximation to 3μ . Thus, it is appropriate to determine shearing module μ that constitutes the most significant parameter of the viscoelastic environment measured.

Please replace paragraph [0063] with the following:

It is therefore not only necessary to know the displacement v_x in the image plane but also to know it around the image plane ~~in order~~ to be able to estimate the second derivative perpendicular to the image plane: $\delta v^2/\delta z^2$. In ~~French patent~~ International Application No. FR 9903157 and the publications in impulsive elastography the second derivative perpendicular to the image plane is eliminated from the equation because it can not be measured experimentally. In fact, v is only measured in the (x,y) plane, only $v(x,y)$ is known. $\delta v^2/\delta z^2$ can not be determined. A known hypothesis consists in posing:

$$\frac{\partial^2 v}{\partial z^2} = 0$$

Please replace paragraphs [0067] through [0070] with the following:

Thus, two solutions are envisaged for measuring $v(x, y, z)$ and calculating $\delta v^2/\delta z^2$:

~~– Either~~ either a 1.5 D 9 bar is used or a wye transducer allowing a focalization at three different points of elevation,

~~– Or~~ the acquisition is reproduced three times by successively shifting the bar in $z-\Delta z$, z and $z+\Delta z$ with Δz judiciously selected in such a manner as to be close to the resolutions obtained at x and y ($\Delta z \cong \Delta x$ and Δy).

If a bar 1.5 D 9 or 1.75 D, shown in ~~figure~~Fig. 4, is used, images 10 can be realized in three planes of the image and the displacements can be calculated in these three planes located, e.g., at $z-\Delta z$, z and $z+\Delta z$. The maximum cadence is nevertheless reduced here by a factor of 3. It is likewise possible to use a wye transducer 11 in which transducers 12 are distributed spatially, as shown in ~~figure~~Fig. 5.

In the second solution, ~~consisting in comprising~~ reproducing the acquisition three times and successively shifting the bar at $z-\Delta z$, z and $z+\Delta z$, it should be noted that it is necessary that the viscoelastic environment to be measured did not move between two acquisitions and that the applied low-frequency applied force is synchronized for each position in elevation.

In the case of a double mechanical scan, that is, one comprising either two bars 5, 6 or one bar moving along two axes, all the components of the tissular speed vector are known. A more general case (compressible environment) ~~consists in comprises~~ using the Navier equation, that is written:

$$\rho \frac{\partial^2 \vec{v}}{\partial t^2} = (\lambda + \mu) \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) + \mu \vec{\nabla}^2 \vec{v}$$

Please replace paragraphs [0073] through [0074] with the following:

It can be understood with the above equation why neglecting the tissular speeds linked to the compression waves is a source of error. To be sure, the tissular speeds linked to the compression waves are low compared to those generated by the shearing wave; ~~however~~. However, their contribution can not be neglected because the coefficient λ in factor is great in front of the compression term. The discretization of this equation can be realized if the three components of the tissular speed

vector are known. In fact, this equation causes couplings to intervene between the evolutions of the tissular speeds in all directions.

The invention ~~proposes using~~uses a mounting or device such as is shown in ~~figure~~Fig. 6. This device permits the measuring of the three components of the tissular speed vector in the organ studied while successively scanning the environment along three different axes 13, 14 and 15. Bar 16 allows the measuring of the tissular along direction y noted u_y , bar 17 for measuring u_x and bar 18 for measuring u_z . The use of an algorithm for measuring transverse displacements can allow the number of scanning zones to be reduced from three to two by eliminating, e.g., bar 18. Displacement u_z would then be determined simultaneously with bar 16 and bar 17, which would allow an average $u_z = (u_{zB1} + u_{zB2})/2$ to be made.

Please replace paragraphs [0077] through [0079] with the following:

Suppose that the shearing waves propagate at 1 m/s in the environment studied and that the main dimension of this environment is 12/8 cm and that the voxels have 1 mm³ for dimension. The propagation of the shearing wave in such an environment and with a length of 12/8 cm lasts 128 ms. For a typical cadence of 1,000 shots per second, 128 ultrasonic shots should be realized ~~in order to~~ follow the propagation of the shearing wave. It can then be estimated that at the end of 150 ms the acquisition is concluded. Suppose that the ultrasonic device shifts at the end of 500 ms and that a second series of 128 ultrasonic shots is realized. If three ultrasonic bars are used for acceding to the three components of the displacement, approximately 3 minutes will be required (384 times 500 ms) to acquire all the data necessary for the resolution of the inverse problem. This measuring time can be reduced by interlacing the ultrasonic shots, and 128 shots would then be necessary for one minute of acquisition.

In the case of scanning, one of the difficulties ~~consists in~~comprises maintaining a good coupling between the transducer and the environment studied during the entire duration of the scan. In the case in which the surface of the environment is ~~plane~~planar the scanning can be realized using an ultrasonic coupler, e.g., a water-based gel. When this is not possible or when the surface of the environment is “uneven”, ~~we propose immersing~~ the viscoelastic environment is immersed in water. This ~~case is~~ represented in ~~figure~~Fig. 6 in which the breast 21 of the patient is immersed in parallelepipedic reservoir 22 comprising windows transparent to the ultrasounds and filled with water.

As we have seen above, the device of the invention requires at least one echographic bar. It also requires electronic equipment for ultrasonic acquisition constituted ~~by~~of ultrasonic transmitters and receivers, digital-to-analog and analog-to-digital converters, memories, digital and analog transmission lines, etc. In general, a processing unit that can be, e.g., a PC computer associated with a user interface is added to this electronic equipment dedicated to the digitization of the ultrasonic signals. The elements mentioned in this paragraph are not represented in the various figures but are perfectly known to the expert in the art.

Please replace paragraphs [0081] through [0089] with the following:

In order to alleviate this disadvantage, the device of the invention brings a part of the above-mentioned electronic equipment into the proximity, that is, typically a distance less than 50 centimeters, of the ultrasonic bar with the following consequences:

- ~~An~~an increase in the sensitivity of the system,
- ~~An~~an increase in the energy transmitted,
- ~~A~~a simplification of the connections between the motorized sensor part (bar + brought-up electronic equipment) and the data processing unit (PC or brought-up PC card or DSP processor, etc.),

~~—Aa~~ greater immunity to noise.

These modifications bring about a reduction of the mobility of the bar that would not be compatible with a standard use in echography because echographic bars should be light and manageable. It is important to note that ~~in the case we are concerned with,~~ the mobility of the bar is in any case limited by the course of the scan. The weight of the bar is less important because the bar is not manipulated. It is motorized.

According to one ~~possibility offered by~~aspect of the invention the device ~~proposes to place~~ the analog part of emission and of reception, that is to say, the amplifiers of emission and of reception, in the proximity, that is typically less than 50 ~~[sic—cm?]~~, of the bar while retaining a transmission of analog signals of average levels between the sensor part and the processing unit. In this manner the path of the strong (after amplification) analog emission signals and that of the weak (before amplification) reception signals are reduced, as a consequence of which the reception sensitivity is increased and the transfer of energy to the emission improved.

According another ~~possibility offered by~~aspect of the invention the device ~~proposes to also~~ places the analog-to-digital converters (CAN) and the digital-to-analog converters (CNA) (for the emission and the reception) in the proximity, still typically less than 50 cm (~~centimeters~~), of the bar and to connect the sensor part and the processing unit by a very high-speed digital connection (of the LVDS type, for example). The structure of the device of the invention realized in this manner brings about the following improvements:

~~—The~~ signal-to-jamming ratio to noise is increased by locating the entire analog part at the level of the source. ~~—The;~~ the strong (transmitters) and weak (receivers) analog signals are concentrated at the level of the sensor and no longer traverse the distance between the processing unit and the sensor part;

~~The~~the noise received and the noise emitted are reduced because the connection between the treatment unit and the sensor unit becomes purely digital;

~~The~~the connection between the command/treatment means and the sensor pat is simplified in terms of the number of wires.

~~Assume that~~As an example, an operator uses a bar of 128 elements and 8 bit converters (CAN and CAN) at 50 MHz for the emission and the reception. If emission and reception are separated in time and all paths are active, the transfer rate of digital data reaches $128 \times 8 \times 50 = 51.2$ gbps (gigabits per second). Currently, 17 high-speed digital connections at 3.125 gbps are sufficient for transmitting this data in real time. By way of comparison, an analog solution would require 128 two-wire connections.

Figure 7 shows the device of the invention in a new mounting. In this ~~variant of the device~~ aspect, two ultrasonic probes 23, 24 are used and ~~are~~ immersed in hermetic container 26 filled with water or some other suitable liquid.

The hermetic container or box is capable of rotating, e.g., a quarter turn in such a manner that probe 23 can not only scan along direction X but also along direction Z. Ultrasonic probe 24 scans solely along direction Z. The acquisition of the ultrasonic signals is therefore made in three times:

- ~~Scanning~~scanning along directions X and Z by two probes 23, 24,
- ~~Rotation~~rotation of hermetic container or box 26 by, e.g., a quarter turn, that is, 90°,
- ~~Scanning~~scanning along direction Z by probe 23.

During the acquisitions, mechanical vibrators 25 inserted in orifices present on the periphery or circumference of hermetic container 26 can be used to produce low-frequency applied forces. One of the two mechanical vibrators or both mechanical vibrators shown in ~~figure~~Fig. 7 can be replaced by a hyperthermal probe and/or an ultrasonic transducer used in remote palpation mode. In the

example selected for illustrating the invention the two orifices present in or on hermetic box 26 are located at 90° from one another, that is to say that the linear mechanical vibrators are positioned perpendicular to one another in such a manner that even after a quarter turn (90°) of container 26 the mechanical vibrators still extend along the same directions, that is, the same straight lines as previously.

The invention was described above by way of example. It is understood that ~~an expert in the art can realize different variants~~ variations of the device and of the process for measuring the elasticity of a human or animal organ and a consecutive establishment of the representation of the elasticity in two or three dimensions, in particular as concerns the arranging or the managing of the different elements constituting this device or their order as well as the importance of the steps of this process are possible without departing from the scope of the ~~patent~~.